

# Rust Operating Systems and Frameworks for Embedded Devices

RustIEC

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ETRO  
ELECTRONICS &  
INFORMATICS

## WHY OPERATING SYSTEMS OR FRAMEWORKS?

- ▶ Timing and Scheduling
- ▶ Resource Management
- ▶ Modularity and Reusability
- ▶ Portability
- ▶ Tooling, Security, Community

# OVERVIEW OF EMBEDDED OS OPTIONS IN RUST

## **Frameworks**

**Embassy** Framework with async executor and async HALs

<https://embassy.dev/>

**RTIC** Real-Time Interrupt-driven Concurrency

<https://rtic.rs/>

## **Operating Systems**

**Tock OS** Microkernel

<https://tockos.org/>

**Hubris** Monolithic kernel

<https://hubris.oxide.computer/>



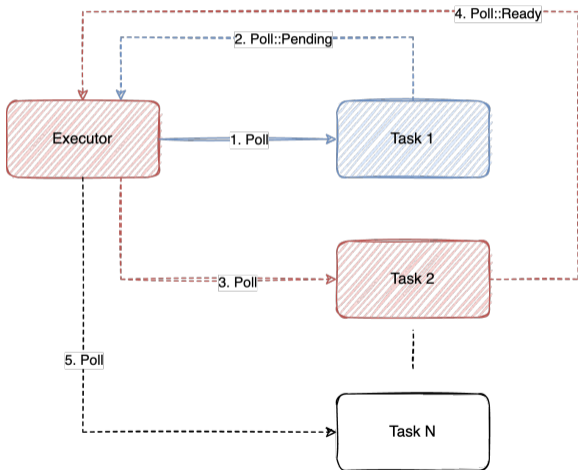
- ▶ **Embedded** meets **as(s)ync** Rust
- ▶ Async Executor for embedded devices

Supported platforms	ARM Cortex-M, RISC-V32, AVR, WASM, std
License	MIT or Apache-2.0
Stars on Github	4.6k
Contributors	332

# EMBASSY

## ASYNC EXECUTOR

```
#[embassy_executor::task]
async fn blink(pin: AnyPin) {
    let mut led = Output::new(pin);
    loop {
        led.set_high();
        Timer::after_millis(150).await;
        led.set_low();
        Timer::after_millis(150).await;
    }
}
```





- ▶ Async capable Hardware Abstraction Layers (HALs) (STM32, nRF, ESP32)
- ▶ Network stack built using smoltcp
  - ▶ IPv4, IPv6
  - ▶ TCP, UDP, ICMP, DHCP, ARP
  - ▶ IEEE 802.3 (Ethernet), IEEE 802.15.4 + 6LoWPAN

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- ▶ Async Executor for embedded devices
- ▶ HALs with async capabilities (mainly STM32, nRF and ESP32)
- ▶ Network stack based on smoltcp
- ▶ Runs on many platforms: STM32, nRF, ESP32, etc.
- ▶ Lots of examples and documentation

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- ▶ Real-Time Interrupt-driven Concurrency
- ▶ Macro-based API for defining tasks and resources
  - ▶ Only ARM Cortex-M and RISC-V supported

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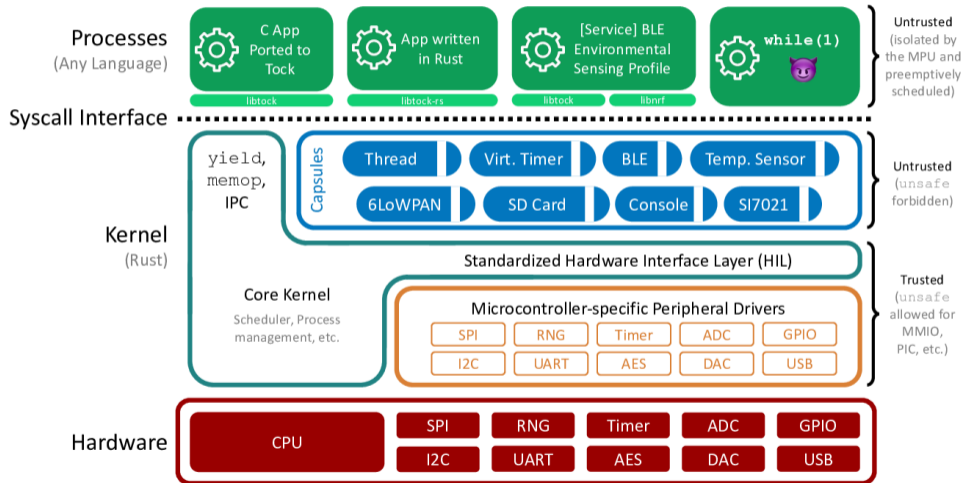
```
#[app(device = nrf528xxx_hal::pac)]
mod app {
    #[shared]
    struct Shared {}
    #[local]
    struct Local {
        led: PA5<Output<PushPull>>,
        state: bool,
    }

    #[init]
    fn init(cx: init::Context) -> (Shared, Local) { /*...*/ }
    #[task(local = [led, state])]
    fn blink(cx: blink::Context) { /*...*/ }
    #[task(local = [led, state])]
    fn state_update(cx: state_update::Context) { /*...*/ }
}
```



- ▶ Macro-based API for defining tasks and resources
- ▶ Prevent deadlocks with Stack Resource Policy
- ▶ No HAL or async capabilities (Embassy executor can be used)
- ▶ No network stack (smoltcp can be used)
- ▶ Only ARM Cortex-M and RISC-V supported

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- ▶ Memory Protection Unit for application isolation
- ▶ Prevent **unsafe** code in applications and capsules (drivers)
- ▶ Own network stack (only support IPv6 over IEEE 802.15.4)
- ▶ Own executable binary format
- ▶ Support for many microcontrollers

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- ▶ Only support for platforms they use (some STM32 microcontrollers)
- ▶ Tasks defined in an **application configuration file**
- ▶ Memory Protection Unit for task isolation
- ▶ Tasks compiled separately and statically linked
- ▶ Synchronous IPC using Rust's borrowing rules
- ▶ Network task built using smoltcp

Supported platforms	ARM Cortex-M, RISC-V32
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- ▶ Focus on robustness
- ▶ Not many platforms supported
- ▶ Tasks defined in an application configuration file
- ▶ Memory Protection Unit for task isolation
- ▶ Network stack built using smoltcp

Supported platforms	ARM Cortex-M, RISC-V32
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# COMPARISON

<b>Feature</b>	<b>Embassy</b>	<b>RTIC</b>	<b>Tock OS</b>	<b>Hubris</b>
Async capabilities	●	◐	◐	◐
Network Stack	●	○	◐	●
Task Isolation	○	○	●	●
Code size	●	●	◐	○
Platform Support	●	◐	●	○
Documentation & Examples	●	●	●	○
Community Support	●	●	●	○

**RIOT-rs** A port of RIOT-OS to Rust.  
Built using the Embassy framework + threads.  
Very experimental.



## OTHERS

**RIOT-rs** A port of RIOT-OS to Rust.  
Built using the Embassy framework + threads.  
Very experimental.

**Others** aerugo, bern, drone, lilos, MnemOS, tornado, wasefire, ...

## CONCLUSION

RTIC For small projects without network stack

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Embassy For more complex projects with a network stack

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Tock OS For advanced projects (multiple applications)

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RTIC For small projects without network stack

Embassy For more complex projects with a network stack

Tock OS For advanced projects (multiple applications)

Hubris For very robust projects

Questions?